Communication Avoiding LU with Tournament Pivoting in SLATE

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Contents

List of Figures i
List of Tables i

1 Introduction 1

2 Communication Avoiding LU Factorization Algorithm 1
   2.1 Overview ................................................................. 1
   2.2 Implementation Details ........................................... 1
   2.3 CALU Algorithm in SLATE ..................................... 2

3 Performance Results 7

References 9

List of Figures

1 Panel Factorization of CALU ........................................... 2
2 CALU numerical kernels and the involved inter-communication. The highlighted tiles presents the working set of each row, where red color denotes input tiles and black color denotes input/output tiles ........................................... 3
3 Performance of LU variant in SLATE on 16 nodes of Shaheen-II. 7
4 Strong scaling results on Shaheen-II ................................ 8
5 Overhead of CALU panel factorization of 80k matrix size and 320 tile size on 16 nodes of Shaheen-II ......................................................... 8
6 Performance of LU tnt piv and LU RBT on Summit .................. 9
7 CALU based on local and global tree reduction ....................... 10

List of Algorithms

2.1 Panel factorization, getrf_tnt piv and lower trsm computational routines .... 4
2.2 Trailing Lookahead update, upper trsm and gemm and computational routines .... 5
2.3 Trailing update of the remaining matrix, upper trsm and gemm and computational routines ......................................................... 6

List of Tables
1 Introduction

SLATE (Software for Linear Algebra Targeting Exascale) \(^1\) is being developed as part of the Exascale Computing Project (ECP) \(^2\), which is a joint project of the U.S. Department of Energy’s Office of Science and National Nuclear Security Administration (NNSA). The objective of SLATE is to provide distributed, GPU-accelerated dense linear algebra capabilities to the US Department of Energy and to the high-performance computing (HPC) community at large.

This report discusses the implementation of communication avoiding LU algorithm in SLATE. It is based on tournament pivoting strategy, that is shown to be stable in practice.

2 Communication Avoiding LU Factorization Algorithm

2.1 Overview

Since the cost of data communication has significantly outpaced the costs of calculations on current and future architectures, we are motivated to use algorithms that communicate as little as possible at the expense of doing more computation, or storing redundant data. Therefore, we extend the current implementation of the LU factorization in SLATE using the tournament pivoting strategy designed by Grigori et al \([1]\). It is called Communication-Avoiding LU factorization (CALU) and it has been proven to be stable in practice \([2]\). The main idea of CALU is to reduce the number of messages exchanged during the panel factorization by performing redundant arithmetic operations. The main difference between CALU and classical LU (i.e partial pivoting LU) lies in the panel factorization. In LU, the processors need to synchronize for each column of the panel, while in CALU processors need to synchronize only for each column block of the panel.

2.2 Implementation Details

The panel factorization using CALU is illustrated in Fig. 1. The algorithm presented in this report bears some similarities to Communication-Avoiding QR (CAQR) described in \([3]\). CALU divides the panel into tiles of size \(b\) and distributes those tiles following block cyclic distribution. First, each processor performs standard LU on its local tiles (equivalent of the LAPACK \texttt{getrf} routine) to identify in parallel pivot rows, applies the resulting permutation vector on the original local tiles, then keeps the first \(b\) rows of its permuted local blocks as the pivot candidates for the next level in the computation. This step is represented by the dash arrows in 1. The next step applies a binary tree reduction of the pairwise reductions of the permuted rows, where the pivot candidates are placed one on top another at each node of the tree. Then, LU with partial pivoting is applied again as in the first step. The obtained pivot vector is applied to the original merged tiles and the pivot candidates are chosen for the next level of the reduction. At the end of the reduction step, the good pivot candidate are moved on to the top of the panel with \(L\) and

\(^1\)http://icl.utk.edu/slate/
\(^2\)https://www.exascaleproject.org
The resulting pivot rows are different than the one produced by the standard LU factorization of LAPACK and ScaLAPACK.

The steps of the algorithm are illustrated on Fig. 2. After obtaining a good pivot of the current panel, the algorithm proceeds to update the trailing submatrix, which involves: (1) applying row swaps (LASWAP), (2) upper/lower triangular solve (TRSM), (3) matrix-matrix multiplication (GEMM). This requires the following communication: (1) “horizontal” broadcasting of the panel to the right, (2) “vertical” exchanges of the rows being swapped, and (3) “vertical” broadcasting of the top row or tiles down the matrix.

2.3 CALU Algorithm in SLATE

CALU algorithm is very similar to classical LU algorithm in SLATE. Algorithm in 2.1, 2.2, 2.3 shows the computational routines within #omp pragma task. Algorithm starts iterating over those tasks until it reaches the number of tiles. It consists of four computational kernels i.e., GETRF, TNTPIV (CALU factorization), TRSM (triangular solve), GEMM (general matrix multiply) and LASWAP (row swaps). Moreover, CALU applies same optimization as LU such as lookahead, internal blocking, and cache reuse,
Figure 2: CALU numerical kernels and the involved inter-communication. The highlighted tiles presents the working set of each row, where red color denotes input tiles and black color denotes input/output tiles.
Algorithm 2.1 Panel factorization, `getrf_tntpiv` and lower `trsm` computational routines

```cpp
// panel factorization
#pragma omp task depend(inout:column[k])
{
    auto Apanel = Awork.sub( k, A_mt-1, k, k );
    Apanel.insertLocalTiles();
    // factor A(k:mt-1, k)
    internal::getrf_tntpiv<Target::HostTask>(
        A.sub(k, A_mt-1, k, k), std::move(Apanel), diag_len,
        ib, pivots.at(k), max_panel_threads, priority_one);
    // root broadcasts the pivot to all ranks.
    MPI_Bcast(pivots.at(k).data(),
        sizeof(Pivot)*pivots.at(k).size(),
        MPI_BYTE, A.tileRank(k, k), A.mpiComm());
    // swap rows in A(k+1:A_mt-1, k)
    int tag_k = k;
    internal::permuteRows<target>(
        Direction::Forward, A.sub(k, A_mt-1, k, k),
        pivots.at(k), target_layout, priority_one, tag_k, queue_0);
}

#pragma omp task depend(inout:column[k])
{
    auto Akk = A.sub(k, k, k, k);
    auto Tkk = TriangularMatrix<scalar_t>(Uplo::Upper,
        Diag::NonUnit, Akk);
    internal::trsm<target>(
        Side::Right,
        scalar_t(1.0), std::move(Tkk),
        A.sub(k+1, A_mt-1, k, k),
        priority_one, Layout::ColMajor, queue_0);
    // bcast the tiles of the panel to the right hand side
    BcastListTag bcast_list;
    for (int64_t i = k+1; i < A_mt; ++i) {
        const int64_t tag = i;
        bcast_list.push_back({i, k, {A.sub(i, i, k+1, A_nt-1)}, tag});
    }
    A.template listBcastMT<target>(
        bcast_list, Layout::ColMajor, life_factor_one, is_shared);
}
```
Algorithm 2.2 Trailing Lookahead update, upper trsm and gemm and computational routines

```c
// update lookahead column(s), high priority
for (int64_t j = k+1; j < k+1+lookahead && j < A_nt; ++j) {
    #pragma omp task depend(in:column[k]) \
    depend(inout:column[j]) \
    {
        int tag_j = j;
        internal::permuteRows<target>(
            Direction::Forward, A.sub(k, A_mt-1, j, j),
            pivots.at(k), target_layout, priority_one,
            tag_j, j-k+1);

        auto Akk = A.sub(k, k, k, k);
        auto Tkk = TriangularMatrix<scalar_t>(Uplo::Lower,
            Diag::Unit, Akk);

        // solve A(k, k) A(k, j) = A(k, j)
        internal::trsm<target>(
            Side::Left,
            scalar_t(1.0), std::move(Tkk),
            A.sub(k, k, j, j), priority_one,
            Layout::ColMajor, j-k+1);

        // send A(k, j) across column A(k+1:mt-1, j)
        A.tileBcast(k, j, A.sub(k+1, A_mt-1, j, j),
            Layout::ColMajor, tag_j);

        // A(k+1:mt-1, j) -= A(k+1:mt-1, k) * A(k, j)
        internal::gemm<target>(
            scalar_t(-1.0), A.sub(k+1, A_mt-1, k, k),
            A.sub(k, k, j, j),
            scalar_t(1.0), A.sub(k+1, A_mt-1, j, j),
            host_layout, priority_one, j-k+1);
    }
}

// pivot to the left
if (k > 0) {
    #pragma omp task depend(in:column[k]) \
    depend(inout:column[0]) \
    depend(inout:column[k-1])
    {
        // swap rows in A(k:mt-1, 0:k-1)
        int tag = k;
        internal::permuteRows<target::HostTask>(
            Direction::Forward, A.sub(k, A_mt-1, 0, k-1),
            pivots.at(k), host_layout, priority_zero,
            tag, queue_0);
    }
}
```

Algorithm 2.3 Trailing update of the remaining matrix, upper trsm and gemm and computational routines

```c++
// update trailing submatrix, normal priority
if (k+1+lookahead < A_nt) {
    #pragma omp task depend(in: column[k]) \ 
        depend(inout: column[k+1+lookahead]) \ 
        depend(inout: listBcastMT_token) \ 
        depend(inout: column[A_nt-1])
{
    // swap rows in A(k:mt-1, kl+1:nt-1)
    int tag_kl1 = k+1+lookahead;
    internal::permuteRows<target>(
        Direction::Forward, A.sub(k, A_mt-1, k+1+lookahead, A_nt-1),
        pivots.at(k), target_layout, priority_zero, tag_kl1, queue_1);

    auto Akk = A.sub(k, k, k, k);
    auto Tkk = TriangularMatrix<scalar_t>(Uplo::Lower,
        Diag::Unit, Akk);

    // solve A(k, k) A(k, kl+1:nt-1) = A(k, kl+1:nt-1)
    internal::trsm<target>(
        Side::Left,
        scalar_t(1.0), std::move(Tkk),
        A.sub(k, k, k+1+lookahead, A_nt-1),
        priority_zero, Layout::ColMajor, queue_1);

    // send A(k, kl+1:A_nt-1) across A(k+1:mt-1, kl+1:nt-1)
    BcastListTag bcast_list;
    for (int64_t j = k+1+lookahead; j < A_nt; ++j) {
        // send A(k, j) across column A(k+1:mt-1, j)
        // tag must be distinct from sending left panel
        const int64_t tag = j + A_mt;
        bcast_list.push_back({k, j,
            {A.sub(k+1, A_mt-1, j, j)}, tag});
    }

    A.template listBcastMT<target>(
        bcast_list, Layout::ColMajor);

    // A(k+1:mt-1, kl+1:nt-1) -= A(k+1:mt-1, k) * A(k, kl+1:nt-1)
    internal::gemm<target>(
        scalar_t(-1.0), A.sub(k+1, A_mt-1, k, k),
        A.sub(k, k, k+1+lookahead, A_nt-1),
        scalar_t(1.0), A.sub(k+1, A_mt-1, k+1+lookahead, A_nt-1),
        host_layout, priority_zero, queue_1);
}
```

6
Figure 3: Performance of LU variant in SLATE on 16 nodes of Shaheen-II.

3 Performance Results

Figs. 3 shows performance of four different variant of LU factorization in SLATE: (1) LU no pivoting (LU nopiv) which work well for specific classes of matrices, such as diagonally dominant matrices and totally nonnegative matrix, (2) CALU (LU tntpiv) which is based on tournament pivoting, (3) LU based on Recursive Butterfly Transformation RBT (LU RBT) [4], and (4) LU with partial pivoting (LU PP) [5]. The performance is reported in double precision using 16 nodes of Shaheen-II, Cray XC40 with Dual-Socket 16-core Intel Haswell System. We can notice that CALU and RBT behave similarly and they outperform LU with partial pivoting. CALU achieves 1.16x speedup compared to partial pivoting.

To further assess performance of the implementation, Figs. 4 shows the results when scaling number of node. We can see that for small number of nodes CALU and LU partial pivoting deliver similar performance, However, as we add more node we can notice that communication avoiding LU outperform partial pivoting LU.

Figs. 6 shows the performance of LU tntpiv and LU PP on 8 nodes of Summit each with 6 GPUs. LU PP outperforms LU tntpiv for dominant random matrices because the reduction step overhead in the panel factorization, which is not necessary in the type of matrices. However, for completely random matrices, CALU achieves 1.15x speedup compared to LU partial pivoting.

The critical component of the CALU factorization is the step of factorizing the panel. We assess performance of this step by showing the overhead of the first phase where each node is doing the first LU for its local tiles. And the tree reduction phase. Figs. 5 shows that 42% of the time is spent in this first phase and 39% on tree reduction and the remaining 19% of the panel factorization is spent for different auxiliary SLATE functions such as copy, and tileGetForWriting routines.
Figure 4: Strong scaling results on Shaheen-II.

Figure 5: Overhead of CALU panel factorization of 80k matrix size and 320 tile size on 16 nodes of Shaheen-II.
This pie chart shows that there is a room for improvements. As future work, we propose to do local tree reduction within each node using OpenMP thread, followed by the global tree reduction, as shown in 7.

References


Figure 7: CALU based on local and global tree reduction.